

# Calc-based Mechanics

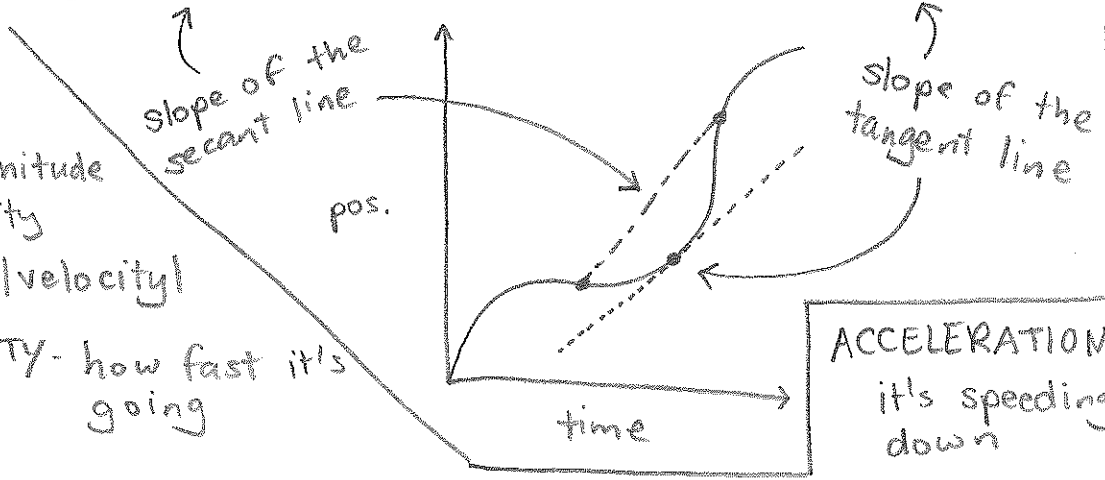
$\Delta x = x_2 - x_1$  DISPLACEMENT - how far something's gone

$v_{avg} = \frac{\Delta x}{\Delta t}$  AVERAGE VELOCITY

$v_{inst} = \frac{dx}{dt}$  INSTANTANEOUS VELOCITY

SPEED - the magnitude of velocity  
Speed = |velocity|

VELOCITY - how fast it's going



$y$  = position  
 $y'$  = velocity  
 $y''$  = acceleration

ACCELERATION - how fast it's speeding up/slowing down

$a_{avg} = \frac{\Delta v}{\Delta t}$  AVERAGE ACCELERATION

$a_{inst} = \frac{dv}{dt}$  INSTANTANEOUS ACCELERATION

(we're assuming you know calculus and how to differentiate and integrate already. If ya don't, learn.)

Vectors: physical quantities with magnitude and direction.

To add vectors, just draw them together and place the tail of the 2nd vector at the head of the 1st.



$x = x_0 + v_0 t + \frac{1}{2} a t^2$

$v = v_0 + a t$

$x - x_0 = \frac{1}{2} (v_0 + v) t$

$t = \frac{v - v_0}{a}$

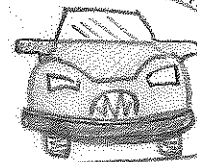
$v^2 = v_0^2 + 2a(x - x_0)$

$g = 9.8 \text{ m/s}^2$

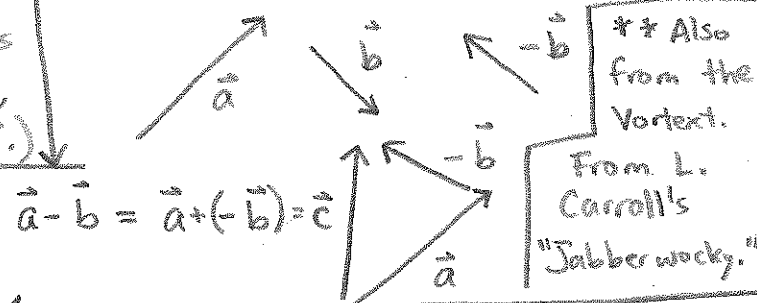
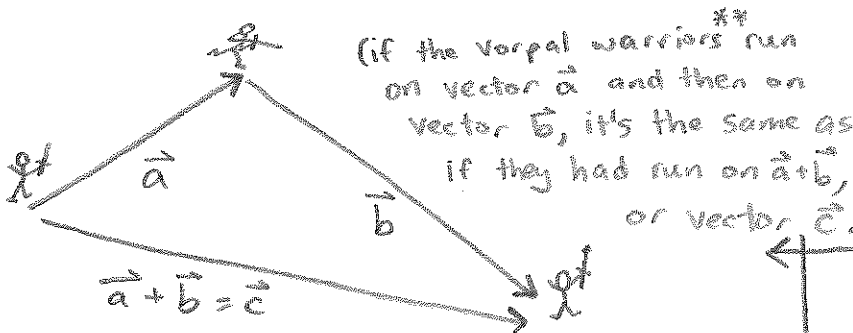
## TOOLS of the

### CONSTANT ACCELERATION

Insert sinister accordion music?  
FROM THE BLACK LAGOON!



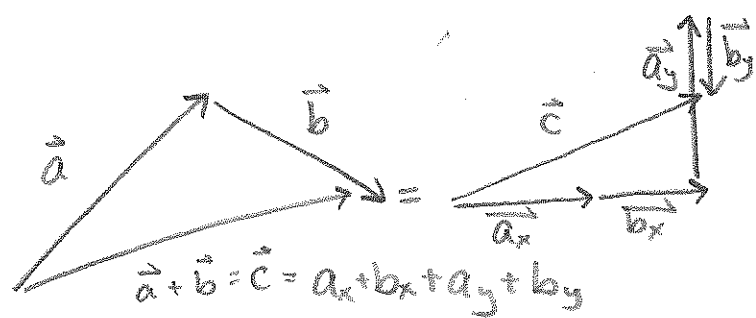
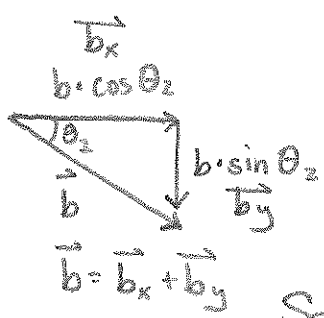
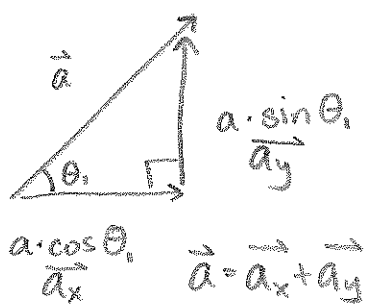
To subtract vectors, take the vector you're subtracting from and flip it around.



\*\* Also from the Vortex.  
From L. Carroll's "Jabberwocky."

\* In The Vortex, a story written in fall 2001, The Froggish One (Katy Dieber, '02) wielded a vector against the forces of Mal'ath. It spun around her fingers, and, when properly wielded, could eliminate both Mal'ath and Geom's vector (by being placed perpendicular to it.)

You can resolve vectors into their components. This makes it easier to add and subtract them.



So to add/subtract vectors, you can split 'em up into x and y vectors and add/subtract those. Use Trig. And Geometry.

$\vec{a}_x = a_x \hat{i}$   
 $\vec{a}_y = a_y \hat{j}$   
 $\vec{a}_z = a_z \hat{k}$

there's also this way of writing it.

vectors - magnitude + direction  
scalars - just magnitude

vector \* scalar = vector with same direction and magnitude equal to the product of the scalar and the original vector's magnitude.

We'll let Katarina<sup>†</sup> demonstrate.



I've got a vector and a scalar, \*\* see?

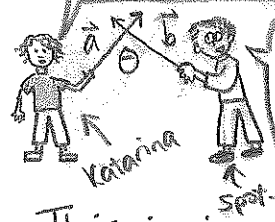
I multiply them together...

$\vec{a} \times 2 =$



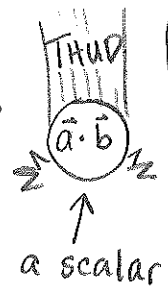
And now I have a vector pointing in the same direction, only twice as big. Nifty.

Now Scott-o-more and I will show you how to multiply vectors.



First the scalar product. Its product is a scalar. Big Surprise.

$\vec{a} \cdot \vec{b} = ab \cdot \cos \theta = \text{DOT PRODUCT}$

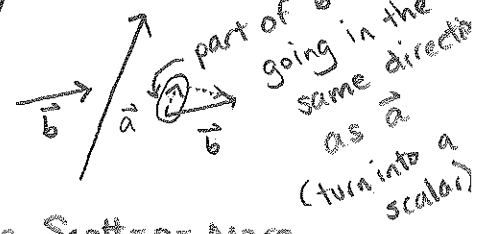


This is the same as having one vector multiplied by the scalar of the other vector that's in the same direction of the first vector.

This is important, so we'll write it again.

**DOT PRODUCT =  $\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z = ab \cdot \cos \theta$**

The dot product is also the sum of the products of each of the component vectors. This comes in handy when you need to find the angle between two vectors.



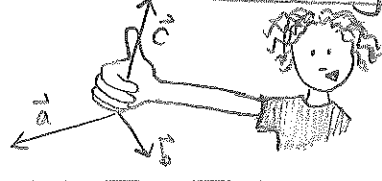
\*\* Written by Scott "Spot" Stiefel, '04. His sophomore year nickname was Scott-o-More.

\*\* Scalars provided courtesy of Fogel-Buddha (Dr. Fogel is a math teacher at IMSA.)

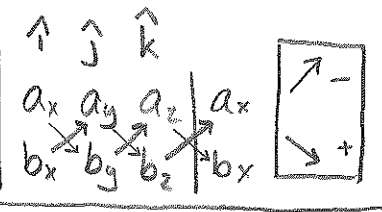
\* The aforementioned "Froggish One."

CROSS PRODUCT =  $ab \cdot \sin \phi = (a_x + a_y + a_z) \times (b_x + b_y + b_z) = \text{another vector}$  (3)  
smaller angle

This'll give you a vector perpendicular to both  $\vec{a}$  and  $\vec{b}$ . Use your right hand to find out which way; sweep your fingers from  $\vec{a}$  to  $\vec{b}$ . Your thumb points in the resulting vector's direction.



Easy memory trick; add all the down-left products, then subtract all the up-right products.



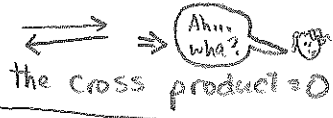
$(a_y b_z - b_y a_z) \hat{i} + (a_z b_x - b_z a_x) \hat{j} + (a_x b_y - b_x a_y) \hat{k} = \text{Cross product}$

For each  $\hat{i} \hat{j} \hat{k}$  term, you use the two other directions.

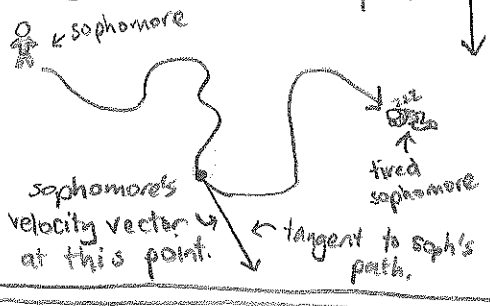
Note that when  $\theta = 90^\circ$ , dot product = 0.\*



Also, when  $\phi = 0^\circ$  or  $180^\circ$ ,



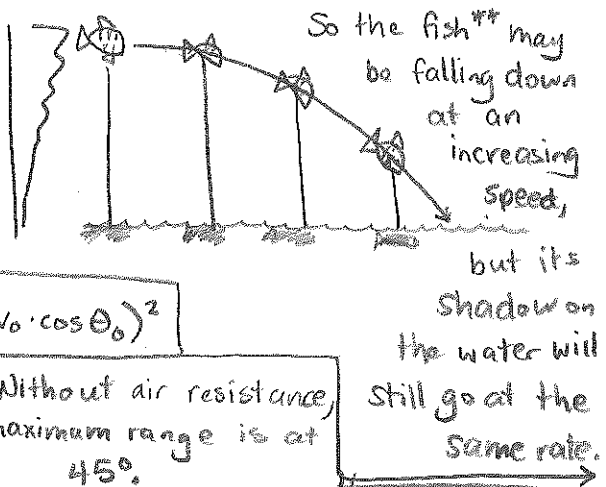
The direction of motion on a 2d plane is the tangent line to the path.



Vertical and horizontal movements are independent of each other.



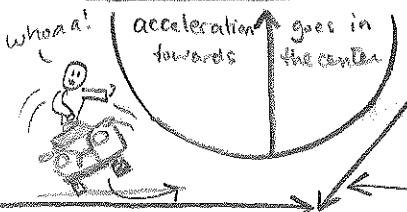
### PROJECTILE MOTION



### CIRCULAR MOTION

$a = v^2/r = \text{CENTRIPETAL ACCEL.}$

$T = \text{period of revolution} = \frac{2\pi r}{v}$



$\text{PATH} = y = (\tan \theta_0)x - \frac{g x^2}{2(v_0 \cos \theta_0)^2}$

$\text{RANGE} = \frac{v_0^2}{g} \cdot \sin(2\theta)$

Without air resistance, maximum range is at  $45^\circ$ .

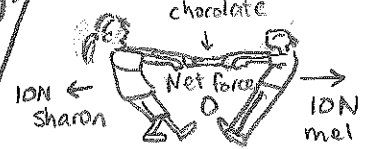
**Newton's 1st Law:**

If no net force acts on a body, then the body's velocity cannot change.

**Newton's 2nd Law:** Force = Mass · Accel.

(note: Mass  $\neq$  weight. Weight = mass · gravity.)

Forces superposition themselves.



**NEWTON'S 3rd LAW:**

Action-reaction: Mel and Sharon pull equally hard on one another.

**NORMAL FORCE**  
 FOUND: PERPENDICULAR TO A SURFACE

**TENSION**  
 FOUND: IN TAUT ROPES OR STRINGS, AWAY FROM THE OBJECT

**FRICTION**  
 FOUND! AWAY FROM THE DIRECTION OF MOTION. MAY BE NEGLECTED TO SIMPLIFY PROBLEMS.

FORCES

$\vec{f}_s$  = static frictional force

$\vec{f}_k < \vec{f}_s$  (usually)  $f_{smax} = \mu_s \cdot N$  = biggest force you can apply before the object moves

$\vec{f}_k$  = kinetic frictional force

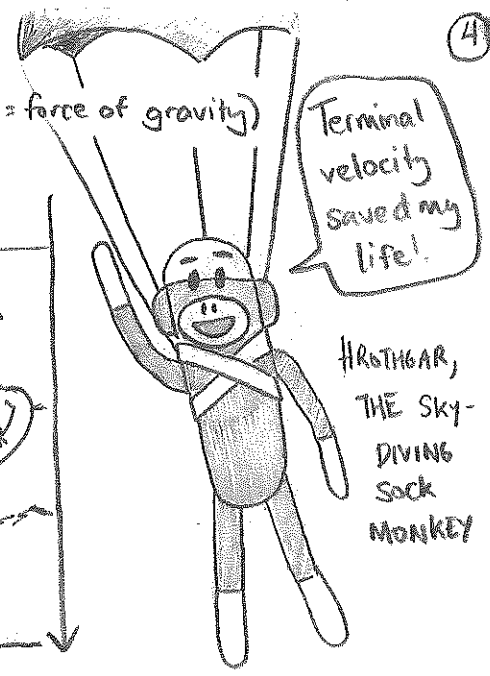
$\mu = \mu_k = \text{Coefficient of friction}$   $f_k = \mu_k \cdot N$  Frictional forces oppose the direction of motion.

\*\* Vorpal Fish, green; owned by Erik Volkman, '03 (Satchel Boy).  
 \* This is the only way to eliminate the vector of Geom and defeat the Mal'ath.

C = drag coefficient. No, we don't mean British comedians in dresses.

TERMINAL VELOCITY =  $v_t = \sqrt{\frac{2F_g}{C_p A}}$  ( $F_g$  = force of gravity)

Drag force =  $\frac{1}{2} C_p A v^2$  ( $\rho$  = fluid density,  $A$  = cross-sectional area)



Let's return to uniform circular motion. Fluffy?\*

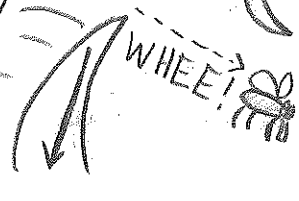
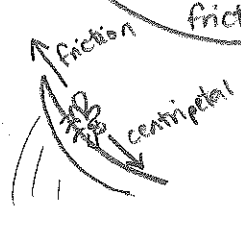
Centripetal acceleration pulls things inwards. If you don't have enough friction or some other force to counteract it, you'll go flying off the curve. Observe.



$a = \frac{v^2}{R}$     $F_{\text{centripetal}} = m \frac{v^2}{R}$

As I swing my tail, the Eumer can hang on because of friction.

But too fast, and the centripetal force is greater than the max fs.

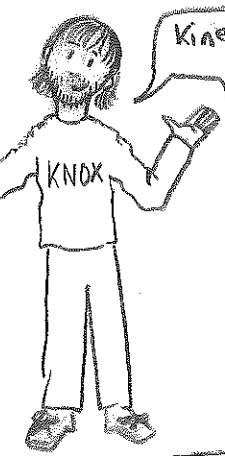


(If, on the other hand, you have no air resistance, a bullet fired at the same instant the monkey falls will hit the monkey if the gun is initially aimed at it, since they'll fall at the same rate.)



Centripetal forces accelerate things by changing their direction, not their speed.

Time to talk about Energy. Here's Thor of Knox\*\*



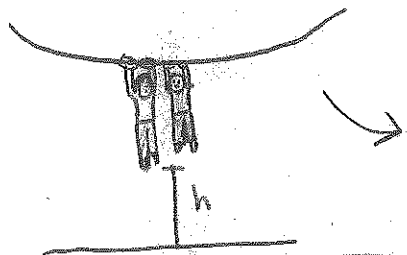
Kinetic energy is when an object is moving. Potential energy is when something could turn into kinetic energy.

For example, look at Mel and Katarina.

They're hanging from a vine. They're not moving. They have potential energy.

Whoop. Now they have kinetic and potential.

Now it's all kinetic at the bottom of their swing.



Potential Energy =  $m \cdot g \cdot h$

Energy is measured in kilogram-meters-squared per second squared. The easy way to pronounce this is "Joules." (or J.)

$KE = \frac{1}{2} M V^2$

NOW WE GO TO WORK.

- Work, n. 1. Energy transferred to/from an object by means of a force on it.
- 2. The bane of students.
- 3. Substitute for sleep.

ENERGY → OBJECT = + WORK  
ENERGY ← OBJECT = - WORK

Work? Gah. Man, I'm outta here.

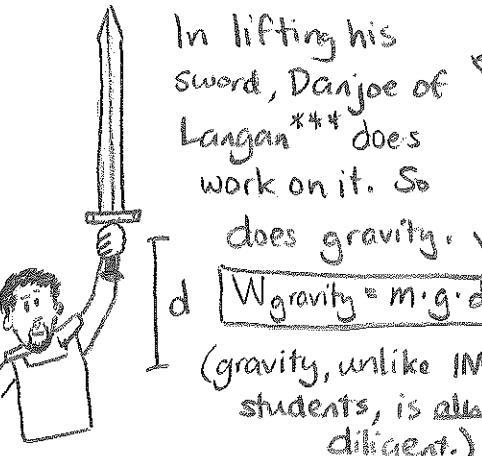
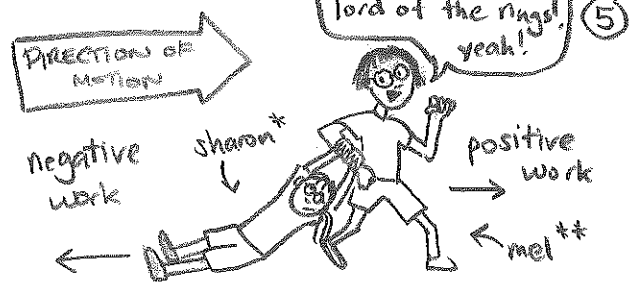


\*\* Matt "Thor" Femrite ('01) of Knox College, an Alosm (departed spirit of the Eemsa bubble.)  
\*\* Symbiont bugs with the Zar Chasms. They congregate in the Pit of Ack during Sudo Festivals.  
\* Sharon David ('03)'s Vortext pet, Fluffy is a Zar Chasm, and grows when cynical remarks are uttered

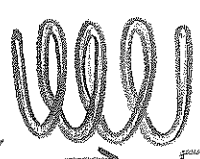
**WORK** =  $\vec{F} \cdot d \cdot \cos \phi = \vec{F} \cdot \vec{d}$  (constant force)

Forces do positive work if they go in the direction of displacement, and negative if they go the opposite way.

$\Delta K = W$  (change in kinetic energy equals the work done.)



$W_{gravity} = m \cdot g \cdot d \cdot \cos \phi$   
(gravity, unlike IMSA students, is *always* diligent.)



**SPRING FORCES**

$F = -kx$  ← Hooke's Law

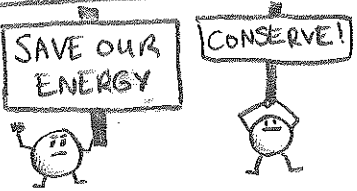
$k$  = spring constant  
stretched spring =  $+x$   
compressed spring =  $-x$

$W_s = \frac{1}{2} kx_i^2 - \frac{1}{2} kx_f^2$  (work done by a spring)

$W = \int_{x_i}^{x_f} F(x) dx$  WORK DONE BY A GENERAL VARIABLE FORCE

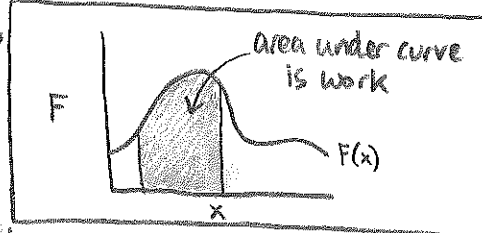
POWER = work per unit time.

$P_{avg} = \frac{W}{\Delta t}$   
 $P_{inst} = \frac{dW}{dt}$   
 $P = \vec{F} \cdot \vec{v}$

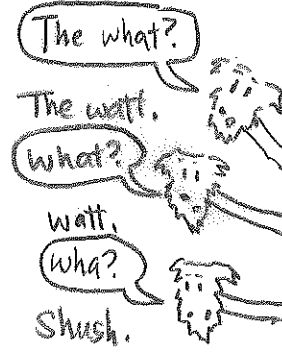


Energy is conserved.  
The change in potential energy  $\Delta U = -\int_{x_i}^{x_f} F(x) dx$  equals the work done to change a system's configuration.

Mechanical Energy =  $K + U$   
(sum of potential and kinetic)

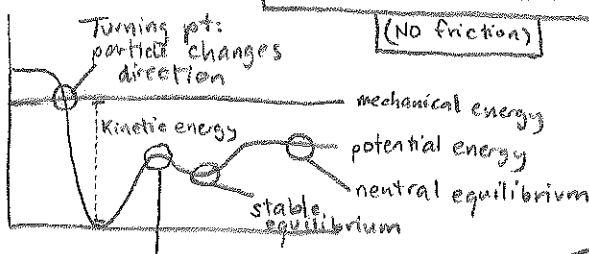


The unit of power, the watt, is one Joule/sec.



$U_y = mgy$  - gravitational  
 $U(x) = \frac{1}{2} kx^2$  - elastic  
CONSERVATION OF POTENTIAL ENERGY

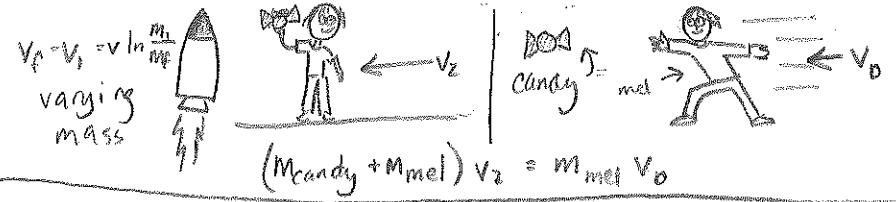
**PE Curves**



$Work = \Delta E_{mechanical}$   
(No friction)

$\Delta E_{thermal} = \int_k d$  (friction sliding)  
 $W = \Delta E_{thermal} + \Delta E_{mechanical}$  (with friction)  
The total energy  $E$  of an isolated system cannot change.

Linear Momentum =  $\vec{p} = M \vec{v}_{com}$  (conserved)



**CENTER OF MASS**

$\frac{1}{M} \sum m_i r_i$  particles  
 $\frac{1}{M} \int x dm$  continuous  
 $\frac{1}{V} \int x dV$  uniform  $\rho$   
 $\rho = \frac{M}{V} = \frac{dm}{dV}$

EXTERNAL  $\Delta E_{mec} = Fd \cdot \cos \phi$  changing  
**IMPULSE**  
 $\vec{J} = \int_{t_i}^{t_f} F(t) dt$   
 $\vec{J} = F_{avg} \Delta t$   
 $\vec{J} = m \Delta v$

**SPRINGYS** 1 dimensional elastic

$v_1 = \frac{m_1 - m_2}{m_1 + m_2} v_0$      $v_2 = \frac{2m_1}{m_1 + m_2} v_0$      $(v_1) \rightarrow (v_2)$

\*\* Joseph Daniel "Danjoe" Langan ('02). The original Keeper of the Lore.  
\*\* Class of '03, Sharon's roommate. Overly obsessed with massive LOTR swordage.  
\* Class of '03. Didn't see Fellowship until Two Towers came out.